

Functional Data Structures in Monoidal Categories

(work in progress)

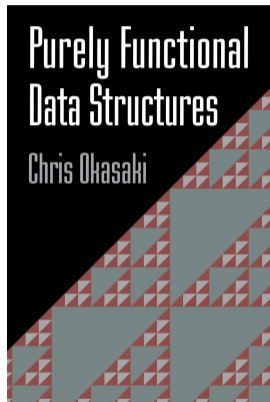
Zhixuan Yang

University of Exeter

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One of the greatest achievements of functional programming is the invention of many purely functional data structures.

Purity implies *persistence*, which is important in text editors, version control systems, databases, ...



[Ok98]

Sequences of data are ubiquitous in programming. A data structure for sequences is

$$S : \text{Type} \rightarrow \text{Type}$$
$$\text{cons} : a \rightarrow S a \rightarrow S a$$
$$\text{snoc} : S a \rightarrow a \rightarrow S a$$
$$(\#) : S a \rightarrow S a \rightarrow S a$$
$$\text{nil} : S a$$
$$\text{matchL} : b \rightarrow (a \rightarrow S a \rightarrow b) \rightarrow b$$
$$\text{matchR} : b \rightarrow (S a \rightarrow a \rightarrow b) \rightarrow b$$
$$\text{splitAt} : \text{Int} \rightarrow S a \rightarrow (S a, S a)$$

satisfying certain equations.

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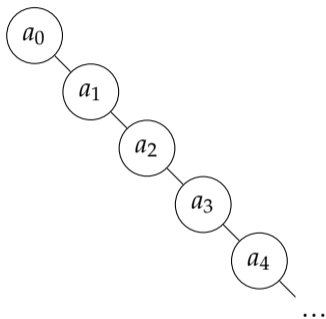
More operations (*head*, *tail*, *lookup*, *fold*, ...) can be defined from the primitives above.

data *List* (*a* : *Type*) **where**

Nil : *List a*

Cons : *a* → *List a* → *List a*

- ▶ Constant time for *cons* and *matchL*.
- ▶ Linear time for other operations.

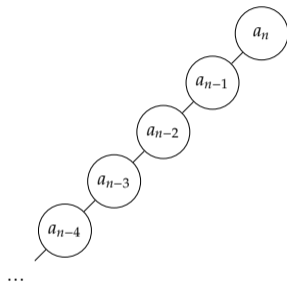


data *SnocList* ($a : \text{Type}$) **where**

Nil : *SnocList* a

Snoc : *SnocList* $a \rightarrow a \rightarrow \text{SnocList } a$

- ▶ Constant time for *snoc* and *matchR*.
- ▶ Linear time for other operations.

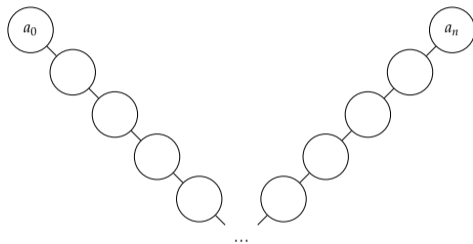


Batched Queue

data *BatchedQueue* (*a* : *Type*) **where**

Q : *List a* \rightarrow *SnocList a* \rightarrow *BatchedQueue a*

- ▶ Constant time for *cons* and *snoc*.
- ▶ Amortised constant time for *matchL*
(in the partially persistent setting).



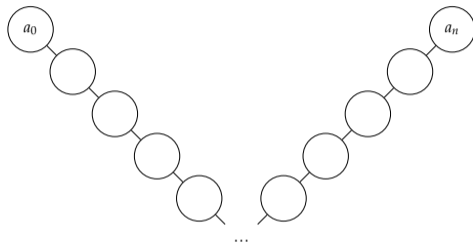
Banker Queue

data *BankerQueue* (*a* : *Type*) **where**

$Q : \text{Int} \rightarrow \text{List } a \rightarrow \text{Int} \rightarrow \text{SnocList } a$
 $\rightarrow \text{BankerQueue } a$

assuming laziness [Oka98].

- ▶ Constant time for *cons* and *snoc*.
- ▶ Amortised constant time for *matchL* (in the fully persistent setting).



Length of the front half \geq length of the rear half.

Balanced Binary Trees

data *AVLTrees* (*a* : *Type*) **where**

Nil : *AVLTrees a*

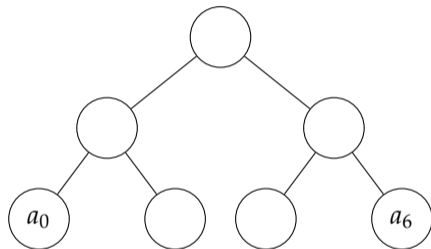
Node : *Int* -- tree height

→ *AVLTrees a*

→ *a*

→ *AVLTrees a*

→ *AVLTrees*



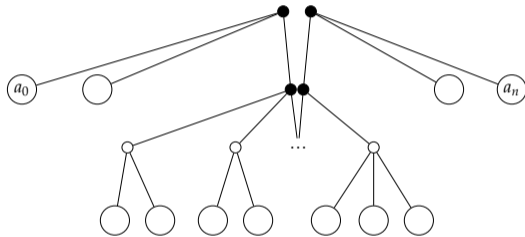
- ▶ Logarithmic time for all operations.

Finger Trees

data *FingerTrees* (*a* : *Type*) **where**

...

- ▶ Amortised constant time for *cons*, *snoc*, *matchL*, *matchR*.
- ▶ Logarithmic time for $\#$ and *splitAt*.



Catenable Lists

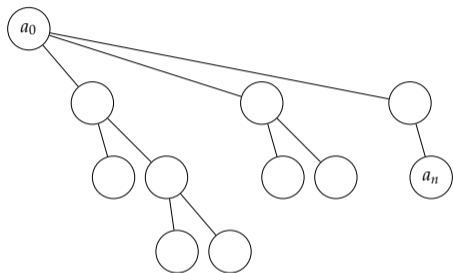
data *CList* (*a* : *Type*) **where**

Nil : *CList a*

Cons : *a* → *Queue (CList a)* → *CList a*

assuming laziness and some *Queue*
supporting *snoc* and *matchL* in $O(1)$.

- ▶ Constant time for *cons*, *snoc*, $\#$,
matchL [Oka98].
- ▶ Linear time for *matchR* and *splitAt*.



Essentially a rose tree with children of a
node stored with a queue.

Observation

These data structures usually are implemented in languages with cartesian contexts (ML, Haskell, Agda, Idris, ...), but *they use data linearly and orderly*.

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These data structures usually are implemented in languages with cartesian contexts (ML, Haskell, Agda, Idris, ...), but *they use data linearly and orderly*.

For example, concatenating two lists is

$$(\#) : List\ a \rightarrow List\ a \rightarrow List\ a$$

$$Nil \quad \# \textit{ys} = \textit{ys}$$

$$Cons\ x\ \textit{xs} \# \textit{ys} = Cons\ x\ (\textit{xs} \# \textit{ys})$$

After all, why would a sequence structure discard/reorder/duplicate its data?

Idea

Linear type theories have semantics in suitable monoidal categories. Let's *interpret these data structures in suitable monoidal categories* to obtain new data structures!

Motivating Example

I am mostly interested in the monoidal category of *endofunctors and composition*.

types A	endofunctors F
terms t	natural transformation $\phi : F \dot{\rightarrow} G$
linear product $A \otimes B$	= functor composition $F \circ G$
lists $List A \cong 1 + A \otimes List A$	free monads $Free F \cong Id + F \circ Free F$
concatenation $(\#)$	multiplication μ

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Question

Can we obtain efficient implementations of free monads from efficient sequence data structures?

Monoidal categories are a strange new world for doing data structures.

Strangeness 1

Lists and free monoids may differ when the monoidal category isn't closed.

To interpret the definition of $\#$, we need not only the universal property of the initial algebra $\mu X. I + a \otimes X$ but also the right adjoint $List\ a \multimap -$ to $- \otimes List\ a$.

$$(\#) : List\ a \rightarrow (List\ a \rightarrow List\ a)$$

$$Nil \quad \# \ ys = ys$$

$$Cons\ x\ xs \# \ ys = Cons\ x\ (xs \# \ ys)$$

Example

Let $\langle \text{MON}, \times, 1 \rangle$ be the cartesian monoidal category of monoids in SET . It is *not closed*.

- ▶ The free monoid over $A = \langle |A|, \cdot_A, \epsilon_A \rangle \in \text{MON}$ is the free commutative monoid on A (following an Eckmann-Hilton argument).

Example

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- ▶ The free monoid over $A = \langle |A|, \cdot_A, \epsilon_A \rangle \in \text{MON}$ is the free commutative monoid on A (following an Eckmann-Hilton argument).
- ▶ The list object $\mu X. 1 + A \times X$ over A has underlying set $\text{List } |A|$, unit $[],$ and element-wise multiplication using \cdot_A and ϵ_A .

Strangeness 2

The costs of accessing the two components of the monoidal product $A \otimes B$ may differ.

In the monoidal category of *Type*-endofunctors and composition,

$x : A, y : B \vdash (f \ x, y) : A' \otimes B$ is interpreted as $f_{BX} : A(BX) \rightarrow A'B(X)$ while

$x : A, y : B \vdash (x, g \ y) : A \otimes B'$ is interpreted as $A \ g_X : A(BX) \rightarrow A(B'X)$.

If A is a container functor, $A \ g_X$ needs to traverse over the container to apply g_X .

Strangeness 3

Isomorphic monoidal structures may have different cost characteristics.

Under suitable foundational assumptions, functor composition $A \circ B$ has the isomorphic co-Yoneda form $\int^{X:Type} AX \times (X \rightarrow B-)$, for which we do not need to map over A to access B .

Strangeness 4

Snoc-lists and *Cons*-lists may differ, depending on how monoidal products \otimes distributes over coproducts.

In the monoidal category of *Type*-endofunctors and composition, we have $(A + B) \circ C \cong (A \circ C) + (B \circ C)$ but not $A \circ (B + C) \cong (A \circ B) + (A \circ C)$.

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Consequently, letting $\text{Iter } A = \mu X. \text{Id} + (X \circ A)$,

$$\begin{aligned}\text{Iter } A &\cong \text{Id} + \text{Iter } A \circ A \cong I + (I + \text{Iter } A \circ A) \circ A \\ &\cong \text{Id} + A + \text{Iter } A \circ A \circ A \\ &\cong \text{Id} + A + (A \circ A) + (A \circ A \circ A) + \dots \\ &\neq \text{Free } A\end{aligned}$$

Strangeness 5

Case analysis of coproducts may only work under certain contexts, depending on how monoidal products \otimes distributes over coproducts.

In an ordered linear context $(\Gamma_l, x : A + B, \Gamma_r)$, the semantics of pattern matching x needs distributivity of \otimes over $+$, which we may not have.

Data Structures in Monoidal Categories

Cons lists and snoc lists work¹ in any monoidal categories with coproducts, relevant initial algebras, right adjoints $A \multimap -$ to $- \otimes A$ for all A .

¹except *matchR* for cons lists, *cons/+#* for snoc lists

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It's a mis-conception that a snoc list is a **reversed list**. $reverse : List\ a \rightarrow List\ a$ needs symmetry but $yank$ does not.

$$yank : SnocList\ a \rightarrow List\ a$$
$$yank\ sx = go\ xs\ Nil\ \mathbf{where}$$
$$go : SnocList\ a \rightarrow List\ a \rightarrow List\ a$$
$$go\ Nil\ ys = ys$$
$$go\ (Snoc\ sx\ x)\ ys = go\ sx\ (Cons\ x\ ys)$$

¹except $matchR$ for cons lists, $cons/\#$ for snoc lists

Data Structures in Monoidal Categories

Banker queues work² in any monoidal category with *copowers*, coproducts, relevant initial algebras, right adjoints $A \multimap -$ to $- \otimes A$ for all A .

²*snoc*, *cons*, *matchL* works but not the others

Data Structures in Monoidal Categories

Banker queues work² in any monoidal category with *copowers*, coproducts, relevant initial algebras, right adjoints $A \multimap -$ to $- \otimes A$ for all A .

The size integers are used non-linearly. We should interpret them as copowers.

```
data BankerQueue (a : Type) where  
  Q : Int → List a → Int → SnocList a → BankerQueue a  
  q : Int → List a → Int → SnocList a → BankerQueue a  
  q lenF f lenR r = if lenF < lenR  
    then Q (lenF + lenR) (f # yank r) 0 Nil  
    else Q lenF f lenR r
```

²*snoc, cons, matchL* works but not the others

Data Structures in Monoidal Categories

Balanced binary trees and finger trees work in any monoidal category with copowers, coproducts, relevant initial algebras, and *bi-closedness* (adjunctions $- \otimes A \dashv A \multimap -$ and $A \otimes - \dashv A \multimap -$ for all A). Symmetry is not necessary!

Data Structures in Monoidal Categories

Balanced binary trees and finger trees work in any monoidal category with copowers, coproducts, relevant initial algebras, and *bi-closedness* (adjunctions $- \otimes A \dashv A \multimap -$ and $A \otimes - \dashv A \multimap -$ for all A). Symmetry is not necessary!

Bi-closedness implies distributivity of \otimes over $+$, allowing us to pattern match variables in any context:

$$\text{rotateL}, \text{rotateR} : \text{AVLTree } a \rightarrow \text{AVLTree } a$$
$$\text{rotateL } (\text{Node } _ p x (\text{Node } _ q y r)) = \text{node } (\text{node } p x q) y r$$
$$\text{rotateR } (\text{Node } _ (\text{Node } _ p x q) y r) = \text{node } p x (\text{node } q y r)$$

Data Structures in Monoidal Categories

With a small tweak, catenable lists work³ in any monoidal category with copowers, coproducts, relevant initial algebras, $- \otimes A \dashv A \multimap -$. *No need for bi-closedness!*

$$(\#) : CList\ a \rightarrow CList\ a \rightarrow CList\ a$$

$$--\ xs\ \# \ Nil = xs$$

$$\Nil\ \# \ ys = ys$$

$$C\ x\ xss\ \# \ ys = C\ x\ (snoc\ xss\ ys)$$

We can't pattern match the second argument when xs is in the context. (This has complexity impact though).

³except for *matchR/splitAt*

Some Monoidal Categories

- ▶ *Symmetric closed*: cartesian closed ones, Day tensor products, tensor products of many algebraic structures, ...

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Non-symmetric *by convention*

- ▶ *Non-symmetric one-sided-closed*: endofunctor and composition, lexicographic products, semi-direct products [Ful16]

Non-symmetric *by nature*

Type Formers à la Carte

We don't want a linear language with a fixed set of type formers, but a menu for *type formers à la carte*:

- ▶ Ordered linear contexts
- ▶ Exchangeable linear contexts
- ▶ Linear products/functions
- ▶ Cartesian products/functions
- ▶ Coproducts
- ▶ Fixed-point types
- ▶ Linear/non-linear adjunctions
- ▶ ...

Typing rules for these are standard [Ben95, PP99, Lam58, YW26, JM10].

I am working on a Haskell library linearity-lab for linear type formers à la carte.

- ▶ all aforementioned type formers and the semantics in *Functor* are implemented;
- ▶ a programming library, *not a formalisation* – general recursion, recursive types, no equational laws.
- ▶ only ordered contexts and zero-or-one-variable contexts (as in CBPV) for now, but exchangeable contexts and graded contexts are planned for future.

Implementation techniques are heavily inspired by [PZ17].

Implementation Design Choices

Design Choice

Type formers are formulated as Haskell type-classes.

For example, the two rules for ordered linear contexts (variable and substitution)

$$\frac{}{x : t \vdash x : t} \qquad \frac{\Delta \vdash M : t_1 \quad \Gamma_l, x : t_1, \Gamma_r \vdash N : t_2}{\Gamma_l, \Delta, \Gamma_r \vdash \text{let } x = M \text{ in } N : t_2}$$

becomes

```
class HasOrdCtx (tm :: LCtx → LType → Type) where  
  var :: tm [(x, t)] t  
  
  llet_ :: tm ctx t1 → tm (ctxL # [(x, t1)] # ctxR) t2  
        → tm (ctxL # ctx # ctxR) t2
```

Design Choice

Use *numerically named variables and equality constraints* for better type inference.

With named variables, we can compute the left and right contexts $ctxL, ctxR$ from the middle context ctx and the whole context ctx' . We define

$$\begin{aligned} llet &:: (HasCtx\ tm, ctx' \sim ctxL \# ctx \# ctxR, (ctxL, ctxR) \sim Split\ ctx\ ctx') \\ &\Rightarrow tm\ ctx\ t_1 \\ &\rightarrow (tm\ [(Fresh\ ctx', t_1)]\ t_1 \rightarrow tm\ (ctxL \# [(Fresh\ ctx', t_1)] \# ctxR)\ t_2) \\ &\rightarrow tm\ ctx'\ t_2 \\ llet\ x\ body &= llet_ @tm @ctxL @ctx @ctxR\ n\ x\ (body\ var) \end{aligned}$$

Implementation Design Choices

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Use *numerically named variables and equality constraints* for better type inference.

Consequently supposing $u :: tm [(1, B)] D$, we don't have to write

$$\begin{aligned}t &:: tm [(0, A), (1, B), (2, C)] E \\t &= llet_ @[(0, A)] @[(2, C)] u (\lambda b \rightarrow \dots)\end{aligned}$$

because *llet* can compute $Split [(1, B)] [(0, A), (1, B), (2, C)] = ([(0, A)], [(2, C)])$

$$\begin{aligned}t &:: tm [(0, A), (1, B), (2, C)] E \\t &= llet u (\lambda b \rightarrow \dots)\end{aligned}$$

Without uniquely named variables this can't be done.

Design Choice

Variable terms are passed around at the meta level.

We can write terms like $llet\ u\ (\lambda b \rightarrow b)$ because

$$\begin{aligned} llet :: (...) &\Rightarrow tm\ ctx\ t_1 \\ &\rightarrow (tm\ [(Fresh\ ctx', t_1)]\ t_1 \rightarrow tm\ (ctxL \# [(Fresh\ ctx', t_1)] \# ctxR)\ t_2) \\ &\rightarrow tm\ ctx'\ t_2 \end{aligned}$$

It feels like programming with HOAS, but under the hood there is no magic:

$$llet_ :: tm\ ctx\ t_1 \rightarrow tm\ (ctxL \# [(x, t_1)] \# ctxR)\ t_2 \rightarrow tm\ (ctxL \# ctx \# ctxR)\ t_2$$

Some Example Programs

Define $L a$ as the fixed-point $L a \cong One + (a \otimes L a)$:

```
type L :: LType → LType           data L_ (a :: LType)
type L (a :: LType) = LFix (L_ a) type instance Decode (L_ a) x = One + (a ⊗ x)
```

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```

The type formers we need for lists:

```
type HasList tm = (HasOrdCtx tm, HasLFun tm, HasLFix tm, HasLProd tm, HasCoProd tm)
```

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```

Programming in the order linear language isn't too different from ordinary Haskell:

```
cayley :: (HasList tm, ...) ⇒ tm ctx (L a) → tm ctx (L a -* L a)
cayley xs = matchL xs (abs $ λx → x) (λx xs → abs (λys → consL x (cayley xs ^ ys)))
app :: (HasList tm, ...) ⇒ tm ctx1 (L a) → tm ctx2 (L a) → tm ctx (L a)
app xs ys = cayley xs ^ ys
```

Some Example Programs

We obtain free monads by interpreting lists in the endofunctor category:

```
type Free :: (Type → Type) → (Type → Type)
```

```
type Free f = Fct[(L (Fct f))]
```

```
injFree :: ∀f x. Functor f ⇒ f x → Free f x
```

```
injFree = asFctMap @[Fct f] $ λ(Vars c) → singL c
```

```
joinFree :: ∀f x. Functor f ⇒ Free f (Free f x) → Free f x
```

```
joinFree = asFctMap @[L (Fct f), L (Fct f)] $ λ(Vars (c, k)) → appL c k
```

Along this line, we can interpret *CList* to obtain an efficient implementation of free monads (not shown here for the lack of time).

Compare with a Manual Translation

Without going through the abstraction of linear logics and monoidal categories, I don't think I can come up with *CListF* directly:

data *Free f a* **where**

Ret :: $a \rightarrow \text{Free } f \ a$

Cons :: $f \ a \rightarrow (a \rightarrow \text{Free } f \ b) \rightarrow \text{Free } f \ b$

data *SnocF f a* **where**

Ret' :: $a \rightarrow \text{SnocF } f \ a$

Snoc :: $\text{SnocF } f \ a \rightarrow (a \rightarrow f \ b) \rightarrow \text{SnocF } f \ b$

data *QueueF f a* **where**

Q :: $\text{Int} \rightarrow \text{Free } f \ a \rightarrow \text{Int} \rightarrow (a \rightarrow \text{SnocF } f \ b) \rightarrow \text{QueueF } f \ b$

data *CListF f a* **where**

E :: $a \rightarrow \text{CListF } f \ a$

C :: $f \ b \rightarrow (b \rightarrow \text{QueueF } (\text{CListF } f) \ a) \rightarrow \text{CListF } f \ a$

$CListF$ is useful for abstract syntax with efficient substitution ($O(1)$ -per-variable).

- ▶ Substitution of free monads is *not capture-avoiding*. If we want capture-avoiding, we can work in the category of nominal sets.
- ▶ An efficient implementation of name abstraction of nominal sets $[\mathbb{A}]X$ is via stateful fresh-name generation.






Note however, in some situations efficient substitution can be implemented more easily, such as having an ‘environment’ [Yan26].





Things I didn't talk about today:

- ▶ a careful complexity analysis of $CListF$
- ▶ the need of memoization for $(f \circ g) y = \exists x. f x \times (x \rightarrow g y)$
- ▶ embedding functors in profunctors for performance

Future directions:

- ▶ Stateful algorithms in monoidal categories
- ▶ Laziness in monoidal categories
- ▶ Algorithmic complexity in monoidal categories

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